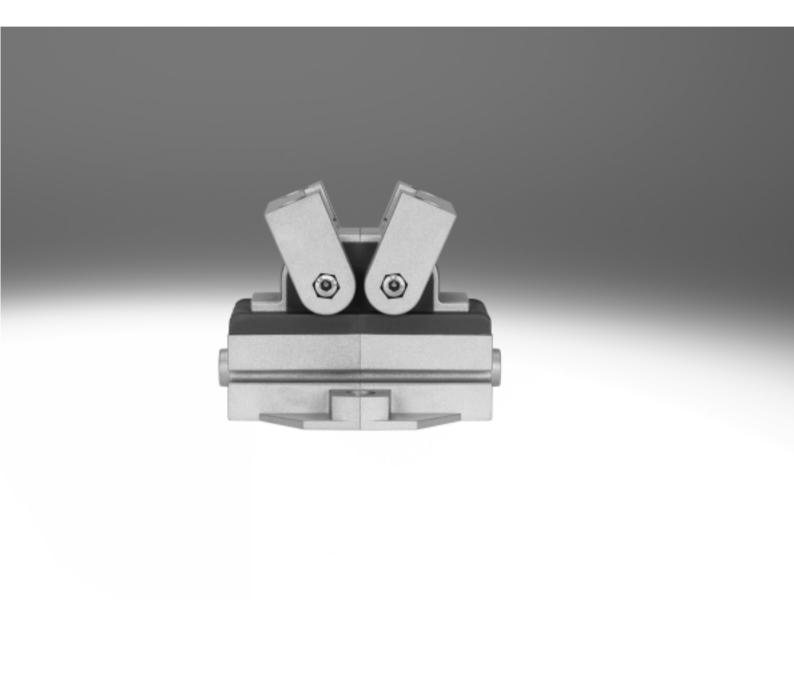
Angle grippers HGWC

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Angle grippers HGWC

Key features

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At a glance

General information

The compact and cost-optimised angle gripper consists of a two-part mirror-symmetrical housing made of die-cast zinc. The force generated by the linear motion of the piston is translated into the gripper jaw movement via a pneumatic piston, which acts directly on the gripper jaws installed in the

housing by means of a moment compensator in accordance with the rack and pinion principle. To ensure a lowbacklash plain-bearing guide for the gripper jaws, appropriate guide elements are fitted in the housing and pretensioned by means of socket head screws.

- Double-acting gripper
- Internal fixed flow control, does away with the need for external flow control in 90% of applications
- High force with minimal volume
- Suitable for external and internal gripping
- Opening angle of 30°, 80°
- Wide range of options for mounting on drives
- Repetition accuracy of 0.05 mm
- Slot for proximity sensor SME/SMT-10

Sizing software for gripper selection

→ www.festo.com

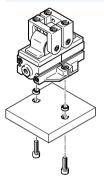
Note

Details

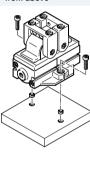


- 1 Gripper jaw
- 2 Housing based on half-shell principle
- 3 Slot for proximity sensor, for sensing the piston position
- 4 Mounting option
- 5 Supply port

Mounting option from underneath

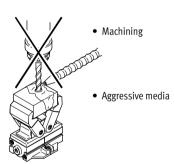


from above





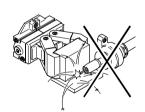
Angle grippers are not designed for the following sample applications:





Grinding dust

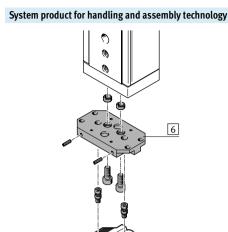
· Welding spatter



Angle grippers HGWC Peripherals overview and type codes

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Peripherals overview 1 2



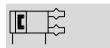
Acces	sories		
	Туре	Description	→ Page/Internet
1	Centring sleeve	For centring when attaching gripper fingers	11
	ZBH	4 included in the scope of delivery of the gripper	
2	One-way flow control valve	For regulating speed	grla
	GRLA		
3	Push-in fitting	For connecting compressed air tubing with standard O.D.	qs
	QS		
4	Proximity sensor	For sensing the piston position	11
	SME/SMT-10		
5	Centring sleeve	For centring when attaching to a drive or plate	11
	ZBH	• 2 included in the scope of delivery of the gripper	
6	Adapter kit	Drive/gripper connections	adapter kit
	HAPG		

Type codes	s			
		HGWC - 12	 40	 A
Туре				
HGWC	Angle gripper			
Size				
SIZE				
JILC				
	angle per gripper jaw			
	g angle per gripper jaw			
Opening				
Opening 15 40	15° 40°			
Opening	15° 40°			

Angle grippers HGWC Technical data

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Function Double-acting HGWC-...-A





Size

12, 16, 20 mm





General technical data				
Size		12	16	20
Design		Rack and pinion		
		Force-guided motion sequence		
Mode of operation		Double-acting		
Gripper function		Angle		
Number of gripper jaws		2		
Max. opening angle	[°]	30, 80		
Pneumatic connection		M5		
Repetition accuracy ¹⁾	[mm]	≤ 0.05		
Max. interchangeability	[mm]	≤ 0.2		
Max. gripper jaw backlash ²⁾	[mm]	≤ 0.1		
Max. gripper jaw angular backlash ³⁾	[°]	≤ 0.5		
Max. operating frequency	[Hz]	≤ 4		
Rotational symmetry	[mm]	≤∅0.2		
Position sensing		Via proximity sensor		
Type of mounting		Via female thread and centring slee	ve	
Mounting position		Any		
Product weight	[g]	200	350	700

- 1) End-position drift under constant operating conditions with 100 consecutive strokes in the direction of movement of the gripper jaws
- Perpendicular to the direction of motion of the gripper jaws
 Pretensioned, backlash-free ball bearing guide

Operating and environmental conditions						
Operating pressure	[bar]	2 8				
Operating medium		Compressed air in accordance with ISO 8573-1:2010 [7:4:4]				
Note on operating/pilot medium		Operation with lubricated medium possible (in which case lubricated operation will always be required)				
Ambient temperature ¹⁾	[°C]	+5 +60				
Corrosion resistance class CRC ²⁾		2				

Note operating range of proximity sensors

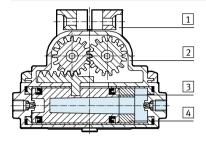
Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or

Angle grippers HGWC Technical data

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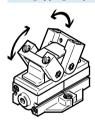
Materials

Sectional view



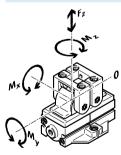
Angl	e gripper	
1	Gripper jaw	Die-cast zinc, painted
2	Housing	Die-cast zinc, painted
3	Piston	Polyamide
4	Distance sleeve	Polyurethane
-	Seals	Polyurethane, nitrile rubber
-	Note on materials	Free of copper, PTFE and silicone
		RoHS-compliant

Total gripping torque at 6 bar



Size		12	16	20
Opening	[Ncm]	22	72	144
Closing	[Ncm]	22	72	144

Static characteristic load values at the gripper jaws



The indicated permissible forces and torques apply to a single gripper jaw. The indicated values include the lever arm, additional applied loads caused by the workpiece or external gripper

fingers, as well as forces which occur during movement.

The zero co-ordinate line (gripper jaw guide) must be taken into consideration for the calculation of torques.

Size		12	16	20
Max. permissible force F _z	[N]	40	60	80
Max. permissible torque M _x	[Nm]	2.5	4	8
Max. permissible torque M _y	[Nm]	0.6	1	1.9
Max. permissible torque M _z	[Nm]	2	3.2	6.7

Angle grippers HGWC Technical data

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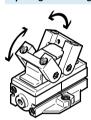
Mass moment of inertia



Mass moment of inertia $[kgm^2x10^{-4}]$ of the angle gripper in relation to the central axis with no load.

Size		12	16	20
HGWCA	$[kgm^2x10^{-4}]$	0.52	1.35	4.31

Opening and closing times [ms] at 6 bar



The indicated opening and closing times [ms] have been measured at room temperature and an operating pressure of 6 bar with vertically mounted gripper and without additional gripper fingers.

The grippers must be throttled for greater applied loads. Opening and closing times must then be adjusted accordingly.

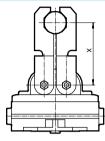
Size		12-15	12-40	16-15	16-40	20-15	20-40
Without external gripper fingers							
HGWCA	Opening	50	70	50	85	50	90
	Closing	35	50	35	70	35	75

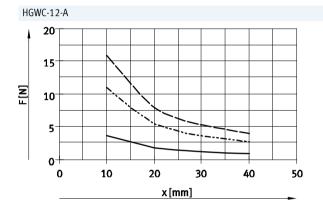
Angle grippers HGWC Technical data

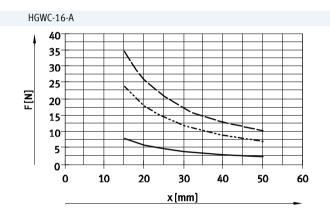
FESTO

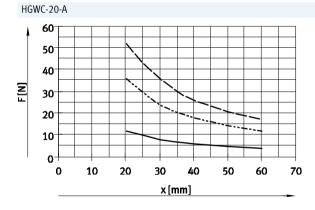
Gripping force F_{Grip} per gripper jaw as a function of operating pressure and lever arm x

Gripping forces as a function of the operating pressure and the lever arm can be determined for the size using the following graph.





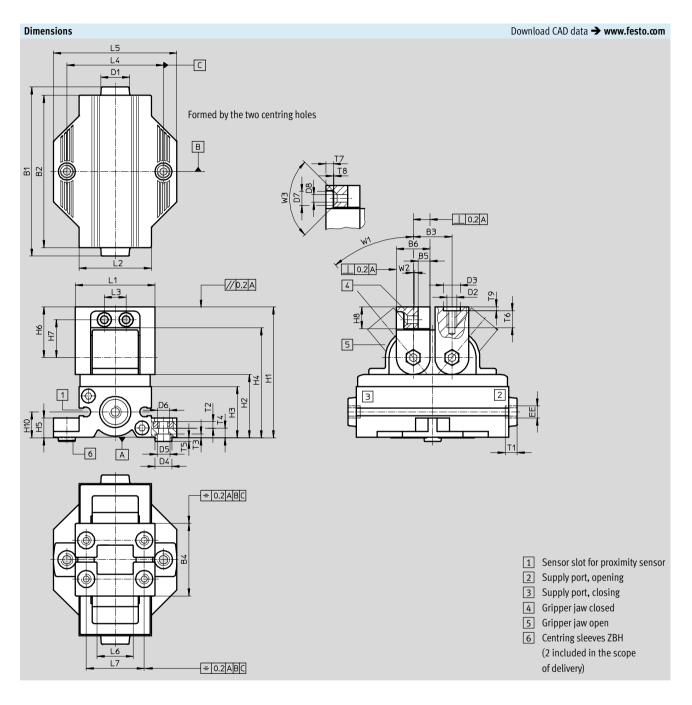




3 bar --- 6 bar -- 8 bar

Angle grippers HGWC Technical data





Angle grippers HGWC Technical data

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Туре	B1	B2	В3	B4 +0.25	B5	В6	D1	D2	D3	D4	D5
			±0.05	+0.25 -0.05	+0.5	+0.1			+0.05 -0.02	F10/h7	
HGWC-12	57	52	12	23	4	11	12	М3	5	7	5.3
HGWC-16	70	63	16	30	5.5	14	12	M4	7	7	5.3
HGWC-20	86	79	20	38	6	18	12	M5	9	9	6.4
Tuna	D/	D.7	Do	EE	H1	H2	Н3	11.6	115	116	H7
Туре	D6	D7	D8	EE	пт	п2	ПЭ	H4	H5	Н6	П/
					±0.5					±0.2	
HGWC-12	M4	4.8	2.6	M5	43.2	20.7	18.2	35.2	6.9	17	12.5
HGWC-16	M5	5.8	3.2	M5	54.2	26.2	21.2	44.7	8.2	21	15.7
HGWC-20	M6	8.1	4.4	M5	68.2	32.7	27	55.7	10.2	26.5	19.5
Туре	Н8	H10	L1	L2	L3	L4 ¹⁾	L5	L6	L7 ¹⁾	T	1
								+0.25			
			±0.2		±0.1			-0.05		mi	n.
HGWC-12	7.5	9.2	27.5	25.5	6	33	42	12	20	4.	5
HGWC-16	9	10.7	33	30	9	40	51	15	24	Į.)
HGWC-20	12	13.7	45	38	12	50	65	21	33		·
Туре	T2	T3	T4	T5	T6	T7	T8	T9	W1	W2	W3
			+0.4	+0.1							
		±0.1	-0.3	-0.3	min.	+0.2		+0.1	±2	±3	
HGWC-12-15	2.2	1.7	3.1	1.3	6	1.7	0.5	1.3	15°	1°	90°
HGWC-12-40	2.2	1./).1	1.5	Ü	1./	0.5	1.5	40°	1	90
HGWC-16-15	2.7	1.8	3.8	1.2	7	3	0.3	1.6	15°	1°	90°
HGWC-16-40	2.1	1.0	ا.0	1.2	,	,	0.5	1.0	40°	1	70
HGWC-20-15	3.2	2.3	5.2	1.7	9	3.5	0.5	2.1	15°	1°	90°
HGWC-20-40	J.2	2.5	7.2	1.,	Í	5.5	0.5	2.1	40°	1	, ,

¹⁾ Tolerance for centring hole ±0.03 Tolerance for thread ±0.2

Ordering data				
	Size	Opening angle	Double-acting	
		[°]	Part No. Type	
	12	30	565135 HGWC-12-15-A	
		80	565141 HGWC-12-40-A	
	16	30	565137 HGWC-16-15-A	
		80	565143 HGWC-16-40-A	
	20	30	565139 HGWC-20-15-A	
		80	565145 HGWC-20-40-A	
Ť				

Angle grippers HGWC Accessories

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Adapter kit HAPG Material:

> Wrought aluminium alloy Free of copper and PTFE RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper com						Download CAD data → www.festo.com			
Combination	Drive	Gripper				Adapter kit			
	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре		
OGSL/HGWC	DGSL	HGWC			HAPG				
. 🖔 "	12, 16	12				529018	HAPG-58		
	20, 25	16			2	191267	HAPG-49		
	20, 25	20				191269	HAPG-51		
SLT/HGWC	SLT	HGWC			HAPG				
× 36	10	12	_			542670	HAPG-100		
	16	12	_			529018	HAPG-58		
	16	16	_			542666	HAPG-101		
	20	16	_		2	191267	HAPG-49		
	20	20	_			542667	HAPG-102		
	25	20	_			191269	HAPG-51		
		I							
ISP/HGWC	HSP	HGWC			HAPG				
	16	16		_		191901	HAPG-55		
₹ '			-	•	2	540882	HAPG-71-B		
	25	20		_		191901	HAPG-55		
			_	•		540883	HAPG-72-B		
ISW/HGWC	HSW	HGWC			HAPG				
***	12	16		_		191901	HAPG-55		
			-	•		540882	HAPG-71-B		
	16	16		_	2	191901	HAPG-55		
			_	•		540882	HAPG-71-B		
ERMB/HGWC	ERMB	HGWC			HAPG				
	20	16	•			542668	HAPG-SD2-42		
	20	20	•		2	542669	HAPG-SD2-43		
	25	20	•			542758	HAPG-SD2-44		
		1	- '						

Corrosion resistance class 2 according to Festo standard 940 070 Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Angle grippers HGWC

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Ordering da	ta – Centring sleeves		Technical data → Inte	rnet: zbh
	For size	Part No.	Type	PU ¹⁾
	[mm]			
	For attachment to a drive or on a plate			
	12, 16	186717	ZBH-7	10
	20	150927	ZBH-9	10
	For attaching gripper fingers			
	12	189652	ZBH-5	10
	16	186717	ZBH-7	10
	20	150927	ZBH-9	10

1) Packaging unit

Ordering data	- Proximity sensors for C-s	lot					
	Type of mounting	Electrical connection,	Switching	Cable length	Part No.	Туре	
		connection direction	output	[m]			
	N/O contact, magneto-resistive Technical data → Ir						
	Insertable in slot from	Cable, 3-wire, in-line	PNP	2.5	551373	SMT-10M-PS-24V-E-2,5-L-0E	
	above	Plug M8x1, 3-pin, in-line		0.3	551375	SMT-10M-PS-24V-E-0,3-L-M8D	
	N/O contact, magnetic reed	Technical data → Internet: sme					
	Insertable in slot length-	Cable, 3-wire, in-line	Contacting	2.5	173210	SME-10-KL-LED-24	
	wise	Plug M8x1, 3-pin, in-line		0.3	173212	SME-10-SL-LED-24	

Ordering data	Ordering data – Proximity sensors for C-slot						
	Type of mounting	Electrical connection,	Switching	Cable length	Part No.	Туре	
		connection direction	output	[m]			
n	N/O contact, magneto-resistive Technical data → Internet: smt						
	Insertable in slot from	Cable, 3-wire, lateral	PNP	2.5	551374	SMT-10M-PS-24V-E-2,5-Q-0E	
(1) S	above	Plug M8x1, 3-pin, lateral		0.3	551376	SMT-10M-PS-24V-E-0,3-Q-M8D	
	N/O contact, magnetic reed Technical data → Internet: sme						
	Insertable in slot length-	Cable, 3-wire, lateral	Contacting	2.5	173211	SME-10-KQ-LED-24	
	wise	Plug M8x1, 3-pin, lateral		0.3	173213	SME-10-SQ-LED-24	

Ordering data – Proximity sensors for C-slot							
	Type of mounting	Electrical connection,	Switching	Cable length	Part No.	Туре	
		connection direction	output	[m]			
A	N/O contact, magneto-resistive					Technical data → Internet: smt	
	Insertable in slot length-	Cable, 3-wire, lateral	PNP	2.5	547862	SMT-10G-PS-24V-E-2,5Q-0E	
	wise	Plug M8x1, 3-pin, lateral		0.3	547863	SMT-10G-PS-24V-E-0,3Q-M8D	
30							

Ordering data − Connecting cables Technical data → I						
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре	
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541333	NEBU-M8G3-K-2.5-LE3	
			5	541334	NEBU-M8G3-K-5-LE3	
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	541338	NEBU-M8W3-K-2.5-LE3	
			5	541341	NEBU-M8W3-K-5-LE3	