FESTO



Cylinders with displacement encoder Product range overview



Function	Туре	Description
Drives	Rodless	
	DDLI	Without guide With contactless measuring displacement encoder Based on linear drive DGC-K Supply ports on end face System product for handling and assembly technology
	DGCI	 With guide With contactless measuring displacement encoder Based on linear drive DGC Supply ports optionally on end face or front System product for handling and assembly technology
	With piston rod	
	DNCI	With contactless measuring displacement encoder Various piston rod variants Standard cylinder to ISO 15552 DIN VDMA
	DDPC	With contactless measuring displacement encoder Various piston rod variants Standard cylinder to ISO 15552 DIN VDMA
	DNC/DSBC	With attached potentiometer MLO-LWG Various piston rod variants Standard cylinder to ISO 15552
Swivel	Swivel module	
module	DSMI	 Based on Swivel module DSM Integrated rotary potentiometer Compact design Wide range of mounting options

Cylinders with displacement encoderProduct range overview



Piston ∅	Stroke/swivel angle	Appropriate						
		For positioning with	For end-position controlle	r	For use as a measuring			
	[mm/°]	CPX-CMAX	CPX-CMPX	SPC11	cylinder			
Rodless								
25, 32, 40,	100, 160, 225, 300, 360, 450,							
63	500, 600, 750, 850, 1000, 1250,							
	1500, 1750, 2000							
	1300, 17 30, 2000		•					
18, 25, 32,	100, 160, 225, 300, 360, 450,							
40, 63	500, 600, 750, 850, 1000, 1250,							
40,03	1500, 1750, 2000							
	1300, 17 30, 2000			•				
With piston r								
32, 40, 50,	10 2000							
63		_	-	-	•			
	100 750							
					-			
80, 100	10 2000							
		-	-	-	•			
	100 750							
		•	•	•	-			
32, 40, 50,	100, 150, 225, 300, 360, 450,							
63, 80	600, 750							
		_	_	•	_			
		-	-	-	-			
Swivel modu								
25, 40, 63	270							
		•	•		•			

Key features



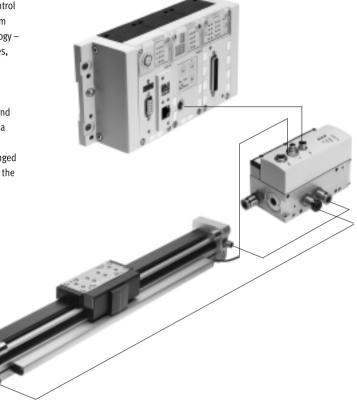
Servopneumatic drive technology

Positioning and Soft Stop applications as an integral component of the valve terminal CPX – the modular peripheral system for decentralised automation tasks.

The modular design means that valves, digital inputs and outputs, positioning modules and end-position controllers, as appropriate to the application, can be combined in almost any way on the CPX terminal.

Advantages:

- Pneumatics and electrics control and positioning on one platform
- Innovative positioning technology piston rod drives, rodless drives, rotary drives
- · Actuation via fieldbus
- Remote maintenance, remote diagnostics, web server, SMS and e-mail alerts are all possible via TCP/IP
- Modules can be quickly exchanged and expanded without altering the wiring



Axis controller CPX-CMAX



Free choice:

Position and force control, directly actuated or selected from one of 64 configurable position sets.

If you are looking for something more:

the configurable function for switching to the next set enables easy functional sequences to be realised with the axis controller CPX-CMAX. All stations are recognised: the auto-identification function identifies each participant with its device data on the controller CPX-CMAX.

Also included:

The range of services of the controller CPX-CMAX includes control of a brake or clamping unit via the proportional directional control valve VPWP.

Up to 8 modules (max. 8 axes) can be operated in parallel and independently of each other. Commissioning via FCT (Festo configuration software) or via fieldbus:

no programming, only configuration.

Technical data → Internet: cpx-cmax

- Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
- You program the system in your PLC environment

Key features



End-position controller CPX-CMPX



Fast travel between the mechanical end stops of the cylinder, stopping gently and without impact in the end position.

Fast commissioning via control panel, fieldbus or handheld unit. Improved control of standstills. Control of a brake or clamping unit via the proportional directional control valve VPWP is an integral part of the controller CMPX.

Depending on the fieldbus chosen, up to 9 end-position controllers can be actuated on the CPX terminal. All system data can be read and written via the fieldbus, including, for example, the mid-positions.

Technical data → Internet: cpx-cmpx

Advantages:

- · Greater flexibility
- OEM friendly commissioning also via fieldbus
- Easy installation and fast commissioning
- Cost-effective
 - Up to 30% faster cycle rates
 - Significantly reduced system vibration
- Improved work ergonomics thanks to significantly reduced noise level
- The extended diagnostics help to reduce the service time of the machine

Proportional directional control valve VPWP



The 5/3-way proportional directional control valve for applications with Soft Stop and pneumatic positioning.
Fully digitalised – with integrated pressure sensors, with new diagnostic functions.
In sizes 4, 6, 8 and 10.
Flow rates of 350, 700, 1400 and

2000 l/min.

With switching output for controlling a brake.

Coloured supply ports.
Pre-assembled cables guarantee
faultless and fast connection with
the controllers CPX-CMPX and
CPX-CMAX.

Technical data → Internet: vpwp

Advantages:

- Easy installation and fast commissioning
- Reduction of system downtimes thanks to the new diagnostic options
- With switching output for controlling a brake/clamping unit

Measuring module CPX-CMIX



Fully digital data acquisition and transmission means that pneumatic cylinders can be used as sensors. With very high repetition accuracy and incorporating both analogue and digital measuring sensors.

Suitable for the linear drive DGCI with displacement encoder for measuring absolute values, for the piston rod drive DNCI/DDPC with incremental displacement encoder or even for a potentiometer of the type MLO.

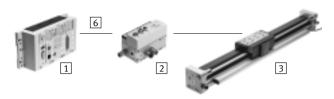
Technical data → Internet: cpx-cmix

- All process steps can be documented, which improves quality
- An adjustable contact force (via pressure regulator) increases the precision of the "displacement sensor"
- With displacement encoders for measuring absolute values, the actual position is immediately available after the system is switched on

Drive options



System with linear drive DDLI, DGCI



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 3 Linear drive DDLI, DGCI with displacement encoder
- 6 Connecting cable KVI-CP-3-...

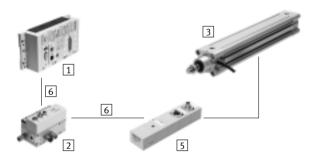
- Pneumatic rodless linear drive with displacement encoder, with or without recirculating ball bearing guide
- Displacement encoder with absolute and contactless measurement
- Diameters:
- DGCI: 18 ... 63 mm
- DDLI: 25 ... 63 mm
- Stroke: 100 ... 2000 mm in fixed lengths
- Range of applications: Soft Stop and pneumatic positioning
- Loads from 1 ... 180 kg
- No sensor interface required

Technical data → Internet: ddli or dgci

Advantages:

- Complete drive unit
- DDLI for easy connection to customer's guide system
- Excellent running characteristics
- For fast and accurate positioning up to ±0.2 mm (only with axis controller CPX-CMAX)

System with standard cylinder DNCI, DDPC



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 3 Standard cylinder DNCI, DDPC with displacement encoder
- 5 Sensor interface CASM-S-D3-R7
- 6 Connecting cable KVI-CP-3-...

Standard cylinder with integrated displacement encoder, conforms to DIN ISO 6432, VDMA 24 562, NF E 49 003.1 and Uni 10 290

- Displacement encoder with contactless and incremental measuring
- Diameter: 32 ... 100 mm
- Stroke: 100 ... 750 mm
- Range of applications: Soft Stop and pneumatic positioning
- Loads from 3 ... 450 kg and a matching sensor interface CASM-S-D3-R7
- Pre-assembled cables guarantee faultless and fast electrical connection

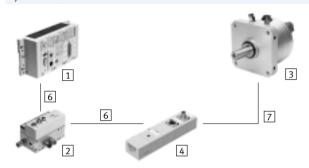
Technical data → Internet: dnci

- · Compact drive unit
- Can be used universally
- · Also with guide unit
- For fast and accurate positioning up to ±0.5 mm (only with axis controller CPX-CMAX)

Drive options



System with swivel drive DSMI



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 3 Swivel drive DSMI with displacement encoder
- 4 Sensor interface CASM-S-D2-R3
- 6 Connecting cable KVI-CP-3-...
- 7 Connecting cable NEBC-P1W4-K-0,3-N-M12G5

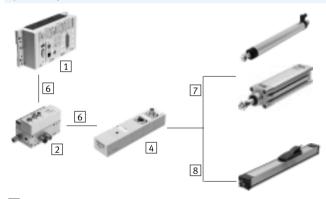
- Swivel drive DSMI with integrated displacement encoder
- Identical design to pneumatic swivel drive DSM
- Absolute displacement encoder based on a potentiometer
- Swivel angle of 0 ... 270°
- Size: 25, 40, 63
- Max. torque: 5 ... 40 Nm
- Range of applications: Soft Stop and pneumatic positioning
- Mass moments of inertia from 15 ... 6000 kgcm² and a matching sensor interface CASM-S-D2-R3
- Pre-assembled cables guarantee faultless and fast connection with the proportional directional control valve VPWP

Technical data → Internet: dsmi

Advantages:

- Complete drive unit, compact, can be used immediately
- High angular acceleration
- With adjustable fixed stops
- For fast and accurate positioning down to ±0.2° (only with axis controller CPX-CMAX)

System with potentiometer



- 1 Controller module CPX-CMPX or CPX-CMAX
- 2 Proportional directional control valve VPWP
- 4 Sensor interface CASM-S-D2-R3
- 6 Connecting cable KVI-CP-3-...
- 7 Connecting cable NEBC-P1W4-K-0,3-N-M12G5
- 8 Connecting cable NEBC-A1W3-K-0,4-N-M12G5

- Attachable potentiometers with absolute measurement, with high degree of protection
- With connecting rod or moment compensator
- Measuring range:
 Connecting rod: 100 ... 750 mm
 Moment compensator:
 225 ... 2000 mm
- Pre-assembled cables guarantee faultless and fast connection with the sensor interface CASM
- Range of applications: Soft Stop and pneumatic positioning with cylinder diameters of 25 ... 80 mm, e.g. DNC or DSBC
- Loads from 1 ... 300 kg

Technical data → Internet: casm

- Easy installation and fast commissioning
- Cost-effective
- Can also be used in harsh operating conditions
- Variety of drives: CPX-CMPX and CPX-CMAX also support cylinders with external displacement encoder

Cylinders with displacement encoderDrive options



System components for Soft Stop systems with end-position controller CPX-CMPX								
	Linear drive	Standard cylinder	Swivel drive	Displacement encoder		→ Page/		
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet		
End-position controller	•	_		_	_	cmny		
CPX-CMPX	-	-	-	-	-	cmpx		
Proportional directional control valve		_	_					
VPWP	-	-	-	-	-	vpwp		
Sensor interface					_	cacm		
CASM-S-D2-R3	_	_	-	-	_	casm		
Sensor interface					_	casm		
CASM-S-D3-R7	_	-	_	_	_	Casiii		
Connecting cable		_	•		_	kvi		
KVI-CP-3	_	_	_	_	_	KVI		
Connecting cable			•	■ / -		nebc		
NEBC-P1W4	_	_	-	- / -	_	певс		
Connecting cable				-/ =		nebc		
NEBC-A1W3	_	_	_	- / -	_	Hebc		
Connecting cable						vnwn		
NEBP-M16W6	_	_	_	_	-	vpwp		

System components for pneumatic po	sitioning systems wi	th axis controller CPX-	CMAX			
	Linear drive	Standard cylinder	Swivel drive	Displacement encod	er	→ Page/
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet
Axis controller		_	_		_	cmay
CPX-CMAX	-	-	-	-	-	cmax
Proportional directional control valve			_			VIDIAID
VPWP	-	-	-	-	-	vpwp
Sensor interface						casm
CASM-S-D2-R3	_	_	-	-	_	Casiii
Sensor interface	_		_	_	_	casm
CASM-S-D3-R7		_	_	_	_	Casiii
Connecting cable		_				kvi
KVI-CP-3	_	_	_	_	_	KVI
Connecting cable			•	■/-		nebc
NEBC-P1W4	_	_	-	- / -	_	lieuc
Connecting cable	_	_	_	- / ■	_	nebc
NEBC-A1W3	_	_	_	- / -	_	lienc
Connecting cable	_	_	_	_		VDWD
NEBP-M16W6	_	_	_	_	_	vpwp

System components for measuring cylinders with measuring module CPX-CMIX									
	Linear drive	Standard cylinder	Swivel drive	Displacement encoder		→ Page/			
	DDLI/DGCI	DNCI, DDPC	DSMI	MLO-LWG/-TLF	MME-MTS	Internet			
Measuring module		_	_	_	_	ami.			
CPX-CMIX-M1-1	-	-	•	-	-	cmix			
Sensor interface			_	_		cacm			
CASM-S-D2-R3	_	_	•	•	_	casm			
Sensor interface						cacm			
CASM-S-D3-R7	_	-	_	_	_	casm			
Connecting cable	(■) ¹⁾			•	(■)	kvi			
KVI-CP-3	(=)-7		-			KVI			
Connecting cable			_	- /-	-	nebc			
NEBC-P1W4	_	_							
Connecting cable				-/ =		nebc			
NEBC-A1W3	_	_	_	- / -	_	HEDC			
Connecting cable						vnwn			
NEBP-M16W6	_	_	_	_	•	vpwp			

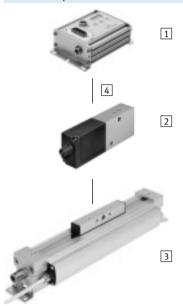
¹⁾ As an extension

Cylinders with displacement encoder Overview



Individual components for positioning with end-position controller SPC11

→ Internet: spc11



- 1 End-position controller SPC11-MTS-AIF-2
- 2 Proportional directional control valve MPYE
- 3 Linear drive DDLI
- 4 Connecting cable KMPYE-AIF-...

Individual components for use as a measuring cylinder with measuring module CPX-CMIX

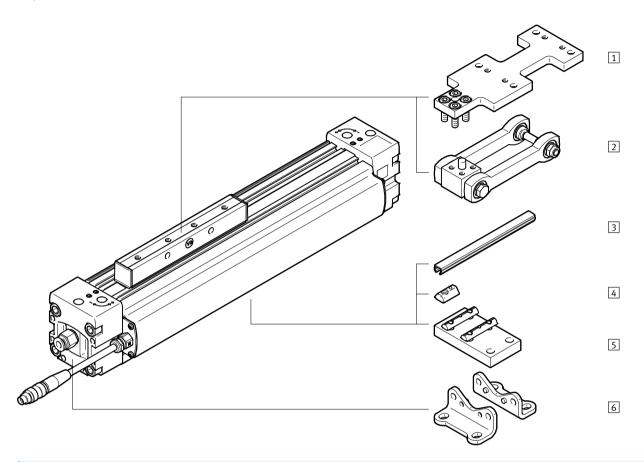
→ Internet: cmix



- 1 Measuring module CPX-CMIX
- 3 Linear drive DDLI

Linear drives DDLI, with integrated displacement encoderPeripherals overview





Acce	ssories		
	Туре	Description	→ Page/Internet
1	Adapter plate DAMF	Has the same interface as the moment compensator FKP for the linear drive DGP	23
2	Moment compensator DARD	For compensating misalignments when using external guides	22
3	Slot cover ABP	For protecting against contamination	24
4	Slot nut ABAN/NST	For mounting attachments	24
5	Central support MUP	For mounting the axis, particularly for long stroke lengths	21
6	Foot mounting HP	For mounting the axis. The foot mounting cannot be used when the bottom mounting position is used for the displacement encoder	21

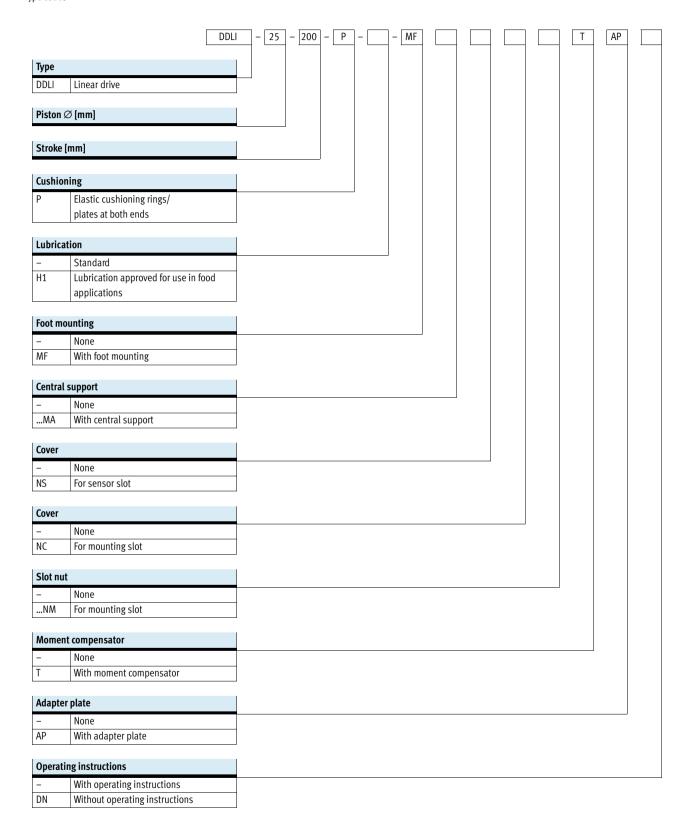


Note

Allocation table of drives and associated proportional directional control valves → 24



Type codes

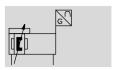


- www.festo.com



Technical data

Function





Stroke length



General technical data						
Piston∅	25	32	40	63		
Design		Rodless linear drive with	slide and displacement en	coder		
Mode of operation		Double-acting				
Moment compensator principle		Slotted cylinder, mechani	ically coupled			
Mounting position	Any					
Type of mounting		Central support				
		Foot mounting				
		Direct mounting				
Cushioning		Elastic cushioning rings/pads at both ends				
Position sensing		Via integrated displacement encoder				
Measuring principle (displacement encoder)		Digital, magnetostrictive, contactless and absolute measurement				
Pneumatic connection ¹⁾		G1/8		G1/4	G3/8	
Stroke ²⁾	[mm]	100, 160, 225, 300, 360	0, 450, 500, 600, 750, 85	0, 1000, 1250, 1500, 17	50, 2000	
Max. speed	[m/s]	3				

- 1) The tubing O.D. applies to pre-assembled push-in fittings ightharpoonup 15
- 2) Note stroke reduction in combination with CPX-CMAX

Operating and environmental conditions						
Piston∅		25	32	40	63	
Operating pressure [I	bar]	2 8			1.5 8	
Operating pressure ¹⁾ [I	bar]	4 8				
Operating medium ²⁾		Compressed air to ISO 85	73-1:2010 [6:4:4]			
Note on operating/pilot medium		Lubricated operation not	possible			
		Pressure dew point 10°C l	below ambient temperature	e/temperature of medium		
Ambient temperature [°C]	-10 +60				
Vibration resistance to DIN/IEC 68 Part 2-6		At 10 60 Hz: 0.15 mm				
		At 60 150 Hz: 2G				
Continuous shock resistance to DIN/IEC 68 Part 2-	-27	Half sine 15 g, 11 ms				
CE marking (see declaration of conformity) ³⁾		To EU EMC Directive				
Certification	ion C-Tick					
Corrosion resistance class CRC ⁴⁾		1				

- 1) Only applies to applications with end-position controller CPX-CMPX, SPC11 and axis controller CPX-CMAX
- 2) The proportional directional control valve VPWP, MPYE used requires these characteristic values
- For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com/sp > User documentation.

 If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.

 Corrosion resistance class CRC 1 to Festo standard FN 940070
- 4) Corrosion resistance class Lik. 1 to resto standard in 940070 Low corrosion stress. For dry indoor applications or transport and storage protection. Also applies to parts behind covers, in the non-visible interior area, and parts which are covered in the application (e.g. drive trunnions).



Forces [N] and impact energy [Nm]							
Piston∅	25	32	40	63			
Theoretical force at 6 bar	295	483	754	1870			
Impact energy at the end positions	0.05	0.12	0.25	0.5			

Positioning characteristics with axis contr	oller CPX-CMA	Х			
Piston∅		25	32	40	63
Mounting position		Any			
Resolution	[mm]	0.01			
Repetition accuracy		→ 15			
Minimum load, horizontal ¹⁾	[kg]	2	3	5	12
Maximum load, horizontal ¹⁾	[kg]	30	50	75	180
Minimum load, vertical ¹⁾	[kg]	2	3	5	12
Maximum load, vertical ¹⁾	[kg]	10	15	25	60
Minimum travel speed	[m/s]	0.05			<u>.</u>
Max. travel speed	[m/s]	3			
Typical positioning time, long stroke ²⁾	[s]	0.65/1.00	0.65/1.05	0.70/1.05	1.05/1.2
Typical positioning time, short stroke ³⁾	[s]	0.38/0.60	0.38/0.60	0.38/0.60	0.65/0.65
Minimum positioning stroke ⁴⁾	[%]	≤ 3		1	<u>, </u>
Stroke reduction ⁵⁾	[mm]	25	25	35	35
Recommended proportional directional con	trol valve				
For CPX-CMAX		→ 24			

¹⁾ Load = payload + load of all moving parts on the drive

⁵⁾ The stroke reduction must be maintained on each side of the drive, the max. stroke for variable positioning is thus: stroke – 2x stroke reduction

Force control characteristics with axis controller CPX-CMAX									
Piston∅		25	32	40	63				
Mounting position		Any							
Maximum controllable force ¹⁾	[N]	266	435	679	1683				
Typical friction forces ²⁾	[N]	20	30	40	50				
Repetition accuracy of pressure control ³⁾⁴⁾	[%]	< ±2		•					

¹⁾ Advancing/retracting at 6 bar

At 6 bar, horizontal mounting position, DDLI-XX-1000, 800 mm travel at min./max. load

³⁾ At 6 bar, horizontal mounting position, DDLI-XX-1000, 100 mm travel at min./max. load

⁴⁾ In relation to the maximum stroke of the drive, but never more than 20 mm.

 $^{2) \}quad \text{These values can fluctuate greatly from cylinder to cylinder and are not guaranteed.} \\$

These friction forces must also be taken into consideration when using an external guide or when the cylinder is moving other components subject to friction

This value defines the repetition accuracy with which the internal differential pressure in the cylinder, which corresponds to the prescribed force setpoint value, is controlled and refers to the maximum controllable

⁴⁾ The effective force at the workpiece and its accuracy depend largely on the friction in the system as well as the repetition accuracy of the internal control system. Note that friction forces always work against the direction of movement of the piston. The following formula can be used as a rule of thumb for the force F at the workpiece:

 $F = F_{setpoint} \pm F_{friction\,forces} \pm repetition\,accuracy\,of\,pressure\,control$

Linear drives DDLI, with integrated displacement encoderTechnical data



Positioning characteristics with Soft S	Positioning characteristics with Soft Stop end-position controller CPX-CMPX, SPC11								
Piston∅		25	32	40	63				
Mounting position		Any							
Repetition accuracy ¹⁾	[mm]	±2							
Minimum load, horizontal ²⁾	[kg]	2	3	5	12				
Maximum load, horizontal ²⁾	[kg]	30	50	75	180				
Minimum load, vertical ²⁾	[kg]	2	3	5	12				
Maximum load, vertical ²⁾	[kg]	10	15	25	60				
Travel time		→ SoftStop eng	→ SoftStop engineering software: → www.festo.com						
Recommended proportional directiona	l control valve								
For CPX-CMPX		→ 24	→ 24						
For SPC11		→ 26							

- One intermediate position. The accuracy in the end positions depends solely on the design of the end stops
 Load = payload + load of all moving parts on the drive

Electrical data – Displacement encoder		
Output signal		Digital
Linearity error ¹⁾	[%]	< ±0.02, min. ±50 μm
Max. travel speed	[m/s]	3
Degree of protection		IP67
CE marking (see declaration of conformity)		To EU EMC Directive ²⁾
Power supply	[V DC]	24 (±25%)
Current consumption	[mA]	Typically 100
Maximum temperature coefficient	[ppm/°K]	15
Electrical connection		Cable with 5-pin plug, round design, M9
Cable length	[m]	1.5
Cable quality		Suitable for use with energy chains

- Always refers to max. stroke.
 For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com/sp → User documentation.
 If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.

Pin allocation of plug



Pir	1	Function
1		24 V
2		n.c.
3		0 V

Pin	Function
4	CAN_H
5	CAN_L
-	Screening

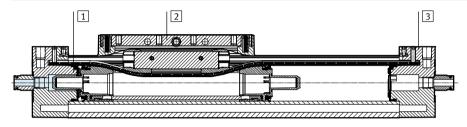
Linear drives DDLI, with integrated displacement encoderTechnical data



Weight [g]				
Piston∅	25	32	40	63
Basic weight with 0 mm stroke	1103	1716	2580	8730
Additional weight per 10 mm stroke	34	43	58	139
Moving mass	130	227	350	1669

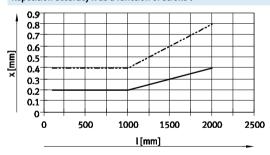
Materials

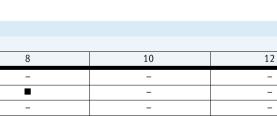
Sectional view



Line	ar drives	
1	Cylinder profile, housing	Anodised aluminium
2	Slide	Anodised aluminium
3	End cap	Painted aluminium
-	Seals	NBR, TPE-U(PU)
-	Cable	Polyurethane
-	Note on materials	Free of copper and PTFE
		RoHS-compliant

Repetition accuracy x as a function of stroke l





Horizontal

----- Vertical

Tubing O.D. of p	pre-assembled push-in fi	ttings			
Size	Stroke	Øin [mm]			
	[mm]	6	8	10	12
DDLI-25	100 160		-	-	-
	225 2000	-		-	-
DDLI-32	100		-	-	-
	160 2000	-		-	-
DDLI-40	100 750	-		-	-
	850 2000	-	-		-
DDLI-63	100 300	-		-	-
	360 450	-	-		-
	500 2000	-	-	-	

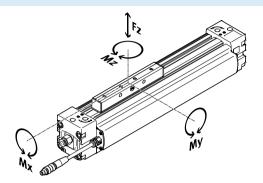
FESTO

Technical data

Characteristic load values

The indicated forces and torques refer to the surface of the slide.

These values must not be exceeded during dynamic operation. Special attention must be paid to the deceleration phase.



If the drive is simultaneously subjected to several of the forces and torques listed below, the following equation must be satisfied in addition to the indicated maximum loads:

$$0.4 \times \frac{Fz}{Fz_{max.}} + \frac{Mx}{Mx_{max.}} + \frac{My}{My_{max.}} + 0.2 \times \frac{Mz}{Mz_{max.}} \leq 1$$

$$\frac{Fz}{Fz_{max.}} \leq 1 \qquad \qquad \frac{Mz}{Mz_{max.}} \leq 1$$

Permissible forces and torques							
Piston∅		25	32	40	63		
Fz _{max} .	[N]	330	480	800	1600		
Mx _{max} .	[Nm]	1.2	1.9	3.8	5.7		
My _{max} .	[Nm]	20	40	60	150		
Mz _{max} .	[Nm]	3	5	8	24		

Linear drives DDLI, with integrated displacement encoderTechnical data



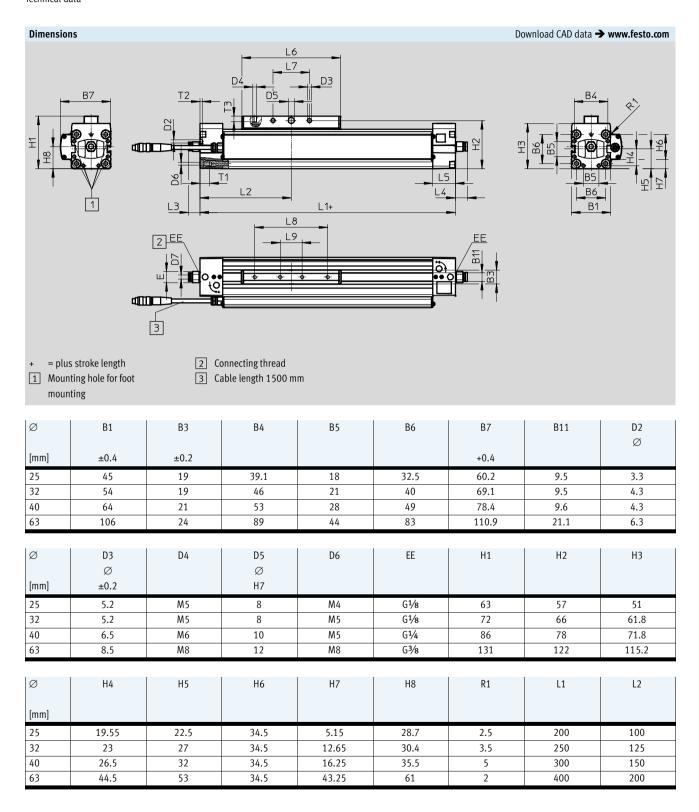
Number of central supports MUP as a function of overall length

Excessive distances between the central supports can reduce the positioning accuracy. The following table shows the required minimum number of central supports and foot mountings.

Stroke [mm]	Number of mounting components		
	Order code MA	Order code MF	
	Central support	Foot mounting +	Central support
	F	I F	1
100 400	2	2	0
401 600	2	2	1
601 1200	3	2	1
1201 1400	3	2	2
1401 2000	4	2	2



Technical data

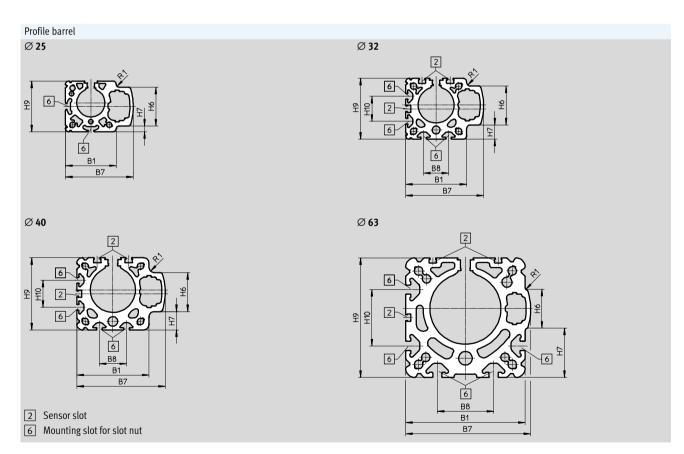


Linear drives DDLI, with integrated displacement encoder Technical data

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Ø	L5	L6	L7	L8	L9	T1	T2	T3
[mm]			±0.1	±0.1	±0.1			
25	25	109	30	50	-,	13	2	7.5
32	31	135	50	100	30	13.2	3	7.5
40	31	171	70	130	40	13.2	3	7.5
63	34	234	110	190	70	21.2	6	12.5

Ø	Stroke	D7	E	L3	L4
[mm]	[mm]				
25	100 160	6	15	15.9	16.4
	225 2000	8	16	21.1	21.6
32	100	6	15	15.9	16.4
	160 2000	8	16	21.1	21.6
40	100 750	8	19	16.6	17.2
	850 2000	10	19	23.6	24.3
63	100 300	8	22	15.8	16.3
	360 500	10	22	19.6	20.2
	600 2000	12	24	25.7	26.3



Ø	B1	В7	B8	H6	H7	Н9	H10	R1
[mm]	+0.4	+0.4				+0.4		
25	45	60.2	-	34.5	5.15	45	-	2.5
32	54	69.1	22	34.5	12.65	54	22	3.5
40	64	78.4	24	34.5	16.25	64	24	5
63	106	110.9	50	34.5	43.3	106	50	2

Linear drives DDLI, with integrated displacement encoder Ordering data – Modular products



Ordering table								
Piston∅		25	32	40	63	Condi-	Code	Entry
						tions		code
M Module No.		1315779	1344778	1463452	1572299			
Function		Linear drive with i	ntegrated displac	ement encoder			DDLI	DDLI
PistonØ	[mm]	25	32	40	63			
Stroke	[mm]	100, 160, 225, 30 2000	00, 360, 450, 50	0, 600, 750, 850, 10	000, 1250, 1500, 1750,			
Cushioning		Elastic cushioning	rings/pads at bot	th ends			-P	-P
Lubrication		Standard						
		Lubrication approved for use in food applications					-H1	
Foot mounting		None						
		1 set					-MF	
Profile mounting		None						
		1 10					MA	
Sensor slot cover		None						
		1 set (for the entire drive length and all slots)					NS	
Mounting slot cover		None						
		1 set (for the entire drive length and all slots)					NC	
Slot nut for mounting slot		None						
		1 50				1	NM	
Moment compensator		None						
		With moment compensator					T	
Adapter plate		None						
		FKP interface				2	AP	
Operating instructions		With operating ins						
		Without operating	instructions				DN	

NM For size 25: Entry "1NM" = delivery quantity 4 pieces
 AP Only with moment compensator T

Transfer order	Iransfer order code																						
		DDLI	-	-		-	Р	-		-													



Accessories



Material: Galvanised steel

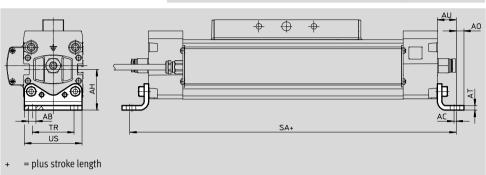
Free of copper and PTFE

- Note

Central supports MUP are
additionally required for strokes
above 400 mm → 17

The foot mounting cannot be used when the bottom mounting position is used for the displacement encoder





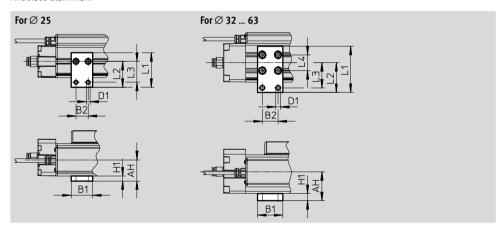
Dimensions a	imensions and ordering data											
For Ø	AB	AC	AH	AO	AT	AU	SA	TR	US	Weight	Part No.	Туре
	Ø											
[mm]										[g]		
25	5.5	2	29.5	6	3	13	226	32.5	44	61	150731	HP-25
32	6.6	2	37	7	4	17	284	38	52	117	150732	HP-32
40	6.6	2	46	8.5	5	17.5	335	45	62	188	150733	HP-40
63	11	3	69	13.5	6	28	456	75	102	305	150735	HP-63

Central support MUP

(Order code: MA)

Material: Anodised aluminium Free of copper and PTFE





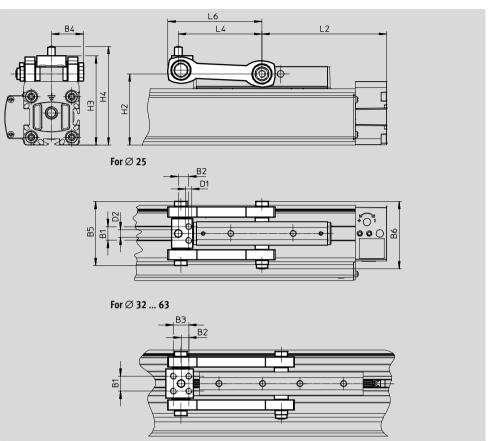
Dimensions a	mensions and ordering data											
For Ø	AH	B1	B2	D1	H1	L1	L2	L3	L4	Weight	Part No.	Туре
				Ø								
[mm]										[g]		
25	29.5	30	17	5.5	7	48	36	29	-	33	1711704	MUP-18/25-P
32	37	35	22	6.6	10	64.5	41.5	35	22	89	150737	MUP-32
40	46	35	22	6.6	14	75	47	40	24	126	150738	MUP-40



Moment compensator DARD

Material: Galvanised steel





Dimensions and ordering data										
	Max. offset between linear drive and external guide $^{1)}$	Max. permissible load in direction of force	Ambient temperature	Weight						
[mm]	[mm]	[N]	[°C]	[g]						
25	±2.5	800	-10 +60	240						
32	±2.5	1300	-10 +60	275						
40	±2.5	2000	-10 +60	580						
63	±4	5000	-10 +60	1000						

1) Laterally and vertically.

For Ø	B1	B2	В3	B4	B5	В6	D1 Ø	D2 Ø	H2
[mm]									
25	11	8.4	-	25.7±2.5	51.4	54	M5x17	6	57
32	12	6.2	12.4	25.7±2.5	51.4	54	M5x13	6	66
40	18	11	17	36±2.5	72	75.3	M6x16	6	78
63	26	12.6	19	44±4	88	96.4	M8x18	10	122

For Ø	Н3	H4	L2	L4	L6	Part No.	Туре
[mm]					max.		
25	71.5±2.5	79±2.5	100	67.1	75.5	2349275	DARD-L1-25-M
32	80.5±2.5	88±2.5	125	80.3	91	2349276	DARD-L1-32-M
40	94.5±2.5	104.5±2.5	150	104	117	2349277	DARD-L1-40-M
63	142±4	152±4	200	138	153	2349279	DARD-L1-63-M

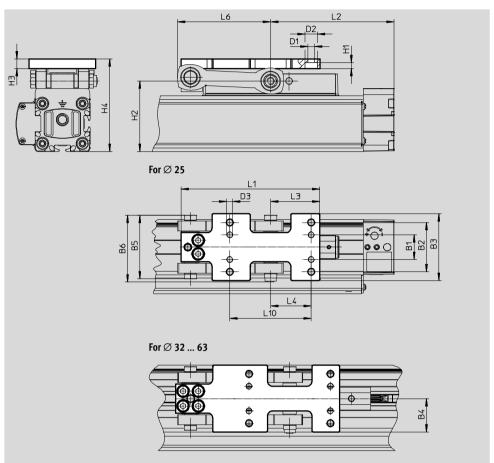
FESTO

Accessories

Adapter plate DAMF

Material: Galvanised steel The adapter plate DAMF has the same interface as the moment compensator FKP for linear drive DGP.





Dimensions a	mensions and ordering data												
For Ø	B1	B2	В3	B4	B5	В6	D1	D2	D3	H1	H2	Н3	
							Ø	Ø					
[mm]													
25	20	40	54	27±2.5	51.4	54	5.5	10	M5	5	57	8	
32	20	40	54	27±2.5	51.4	54	5.5	10	M5	5	66	8	
40	24	44	58	29±2.5	72	75.3	6.6	11	M6	6	78	10	
63	23	51	71	35.5±4	88.1	96.4	9	15	M8	8	122	10	

For Ø	H4	L1	L2	L3	L4	L6	L10	Weight	Part No.	Туре
[mm]						max.				
25	75±2.5	112.4	100	40	33	75.5	66	265	2349282	DAMF-25-FKP
32	84±2.5	133	125	40.5	33	91	66	308	2349283	DAMF-32-FKP
40	99±2.5	162	150	45	38	117	76	593	2349284	DAMF-40-FKP
63	146±4	214	200	61	51	153	102	1042	2349286	DAMF-63-FKP



Ordering data						
	For Ø	Description	Order code	Part No.	Туре	PU ¹⁾
Slot nut ABAN, NST					Technical data → Internet	: hmbn
P	25	For mounting slot	NM	8003032	ABAN-1M4-5	4
Æ	32, 40			150914	NST-5-M5	1
	63			150915	NST-8-M6	
Slot cover ABP					Technical data → Intern	et: abp
	25	For mounting slot	NC	563360	ABP-5-S1	2
	32, 40	Every 0.5 m		151681	ABP-5	
	63			151682	ABP-8	
	25, 32, 40, 63	For sensor slot	NS	563360	ABP-5-S1	2
		Every 0.5 m				

¹⁾ Packaging unit

Ordering data – Proportional di	rectional control v	alves		
	For Ø	Stroke	Proportion	al directional control valve
			Technical d	ata → Internet: vpwp
	[mm]	[mm]	Part No.	Туре
^	For applications	s with axis controller CPX-CMAX		
	25	100 160	550170	VPWP-4-L-5-Q6-10-E
		225 600	550170	VPWP-4-L-5-Q8-10-E
		750 2000	550171	VPWP-6-L-5-Q8-10-E
	32	100	550170	VPWP-4-L-5-Q6-10-E
000000000000000000000000000000000000000		160 360	550170	VPWP-4-L-5-Q8-10-E
a colo		450 2000	550171	VPWP-6-L-5-Q8-10-E
*	40	100 300	550170	VPWP-4-L-5-Q8-10-E
		360 750	550171	VPWP-6-L-5-Q8-10-E
		850 2000	550172	VPWP-8-L-5-Q10-10-E
	63	100 300	550171	VPWP-6-L-5-Q8-10-E
		360 450	550172	VPWP-8-L-5-Q10-10-E
		500 750	550172	VPWP-8-L-5-Q-10-E ¹⁾
		850 2000	1552544	VPWP-10-L-5-Q-10-E-G-EX1 ¹⁾

¹⁾ Push-in fittings for a tubing 0.D. of 12 mm must be used for these stroke ranges.



Ordering data – Proportional di	rectional control v	alves		
	For Ø	Stroke	Proportion	al directional control valve
			Technical d	ata → Internet: vpwp
	[mm]	[mm]	Part No.	Туре
^	For application	s with Soft Stop end-position controller CPX-CMPX, horizont	al	
	25	100 160	550170	VPWP-4-L-5-Q6-10-E
		225 300	550170	VPWP-4-L-5-Q8-10-E
		360 2000	550171	VPWP-6-L-5-Q8-10-E
	32	100	550170	VPWP-4-L-5-Q6-10-E
DO CONTRACTOR OF THE PARTY OF T		160 1000 5501		VPWP-6-L-5-Q8-10-E
000		1250 2000	550172	VPWP-8-L-5-Q-10-E ¹⁾
_	40	100 500	550171	VPWP-6-L-5-Q8-10-E
		600 750	550172	VPWP-8-L-5-Q-10-E ¹⁾
		850 2000	550172	VPWP-8-L-5-Q10-10-E
	63	100 300	550171	VPWP-6-L-5-Q8-10-E
		360 400	550172	VPWP-8-L-5-Q10-10-E
		450	1552544	VPWP-10-L-5-Q-10-E-G-EX1 ²⁾
		500 2000	1552544	VPWP-10-L-5-Q-10-E-G-EX1 ³⁾

- 1) Push-in fittings for a tubing O.D. of 8 mm must be used for these stroke ranges.
- Push-in fittings for a tubing 0.D. of 10 mm must be used for this stroke range.
 Push-in fittings for a tubing 0.D. of 12 mm must be used for these stroke range.

Ordering data - Proportional dir	rectional control v	alves		
	For Ø	Stroke	Proportion	al directional control valve
			Technical d	ata → Internet: vpwp
	[mm]	[mm]	Part No.	Туре
^	For applications	s with Soft Stop end-position controller CPX-CMPX, vertical		
	25	100 160	550170	VPWP-4-L-5-Q6-10-E
		225 750	550170	VPWP-4-L-5-Q8-10-E
		850 2000	550171	VPWP-6-L-5-Q8-10-E
	32	100	550170	VPWP-4-L-5-Q6-10-E
00000		160 300	550170	VPWP-4-L-5-Q8-10-E
		360 1750	550171	VPWP-6-L-5-Q8-10-E
*		2000	550172	VPWP-8-L-5-Q-10-E ¹⁾
	40	100 225	550170	VPWP-4-L-5-Q8-10-E
		300 750	550171	VPWP-6-L-5-Q8-10-E
		850 1000	550171	VPWP-6-L-5-Q-10-E ²⁾
		1250 2000	550172	VPWP-8-L-5-Q10-10-E
	63	100 225	550170	VPWP-4-L-5-Q8-10-E
		300	550171	VPWP-6-L-5-Q8-10-E
		360 450	550172	VPWP-8-L-5-Q10-10-E
		500 2000	1552544	VPWP-10-L-5-Q-10-E-G-EX1 ³⁾

- 1) Push-in fittings for a tubing O.D. of 8 mm must be used for these stroke ranges.
- 2) Push-in fittings for a tubing O.D. of 10 mm must be used for these stroke ranges.

 3) Push-in fittings for a tubing O.D. of 12 mm must be used for these stroke ranges.



Ordering data – Proportional directional control valves							
	For Ø	Stroke	Proportional directional control valve				
			Technical data → Internet: mpye				
	[mm]	[mm]	Part No. Type				
\wedge	For application	For applications with Soft Stop end-position controller SPC11-MTS-AIF-2, horizontal					
9	25	100 160	151692 MPYE-5-1/8-LF-010-B				
		225 300	151692 MPYE-5-1/8-LF-010-B				
		360 2000	151693 MPYE-5-1/8-HF-010-B				
	32	100	151692 MPYE-5-1/8-LF-010-B				
		160 1000	151693 MPYE-5-1/8-HF-010-B				
		1250 2000	151694 MPYE-5-1/4-010-B				
	40	100 500	151693 MPYE-5-1/8-HF-010-B				
		600 750	151694 MPYE-5-1/4-010-B				
		850 2000	151694 MPYE-5-1/4-010-B				
	63	100 300	151693 MPYE-5-1/8-HF-010-B				
		360 400	151694 MPYE-5-1/4-010-B				
		450 2000	151695 MPYE-5-3/8-010-B				

Ordering data - Proportional directional control valves							
	For Ø	Stroke	Proportiona	al directional control valve			
			Technical d	ata → Internet: mpye			
	[mm]	[mm]	Part No.	Туре			
9	For applications with Soft Stop end-position controller SPC11-MTS-AIF-2, vertical						
	25	100 160	151692	MPYE-5-1/8-LF-010-B			
		225 750	151692	MPYE-5-1/8-LF-010-B			
		850 2000	151693	MPYE-5-1/8-HF-010-B			
	32	100	151692	MPYE-5-1/8-LF-010-B			
		160 300	151692	MPYE-5-1/8-LF-010-B			
		360 1750	151693	MPYE-5-1/8-HF-010-B			
		2000	151694	MPYE-5-1/4-010-B			
	40	100 225	151692	MPYE-5-1/8-LF-010-B			
		300 750	151693	MPYE-5-1/8-HF-010-B			
		850 1000	151693	MPYE-5-1/8-HF-010-B			
		1250 2000	151694	MPYE-5-1/4-010-B			
	63	100 225	151692	MPYE-5-1/8-LF-010-B			
		300	151693	MPYE-5-1/8-HF-010-B			
		360 450	151694	MPYE-5-1/4-010-B			
		500 2000	151695	MPYE-5-3/8-010-B			

Ordering data – Connecting cables								
	Description	Cable length	Part No.	Туре				
		[m]						
Connection between axis controller CPX-CMAX/end-position controller CPX-CMPX and proportional directional control valve VPWP								
	Angled plug and angled socket	0.25	540327	KVI-CP-3-WS-WD-0,25				
		0.5	540328	KVI-CP-3-WS-WD-0,5				
		2	540329	KVI-CP-3-WS-WD-2				
		5	540330	KVI-CP-3-WS-WD-5				
		8	540331	KVI-CP-3-WS-WD-8				
	Straight plug and straight socket	2	540332	KVI-CP-3-GS-GD-2				
		5	540333	KVI-CP-3-GS-GD-5				
		8	540334	KVI-CP-3-GS-GD-8				